

Model-Based Development of Embedded Real-Time Systems

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Scope of Interest



Functional

Reliability

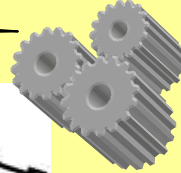
•Data elements per second

Tolerate Faults

Throughput

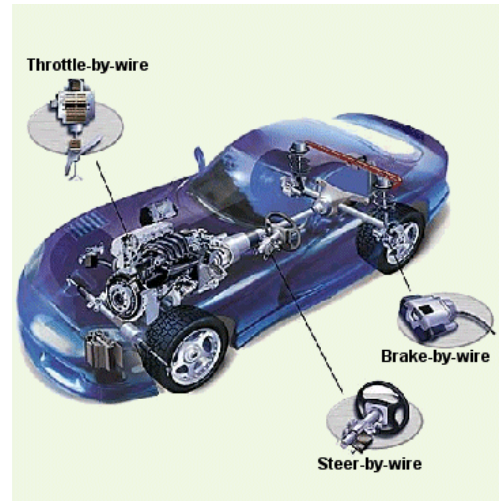
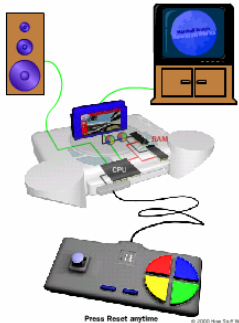


Timeliness

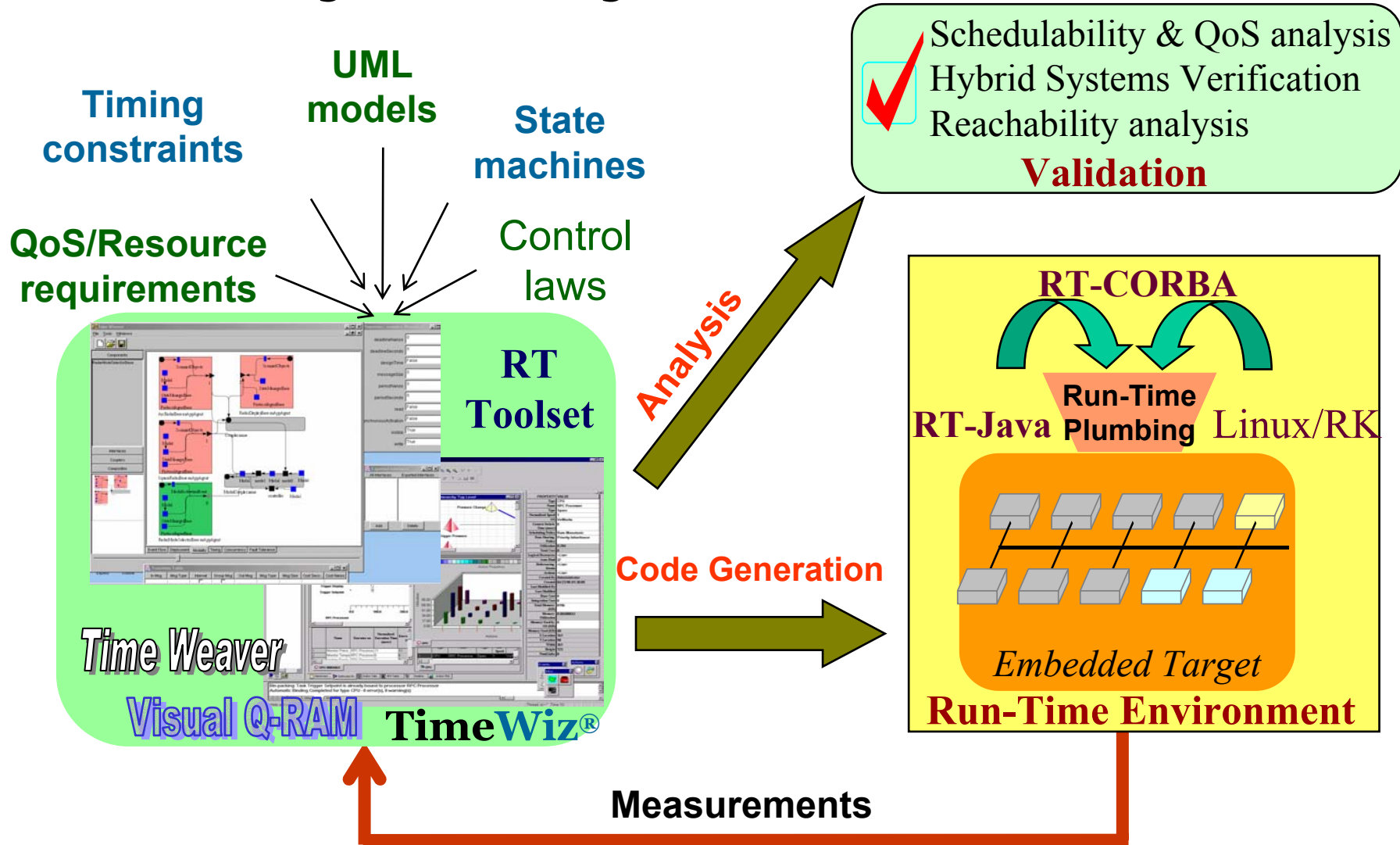


Para-functional

Guarantee End-to-end response time

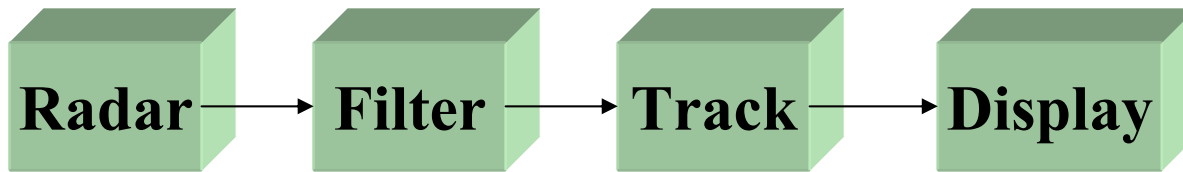


Project Objective



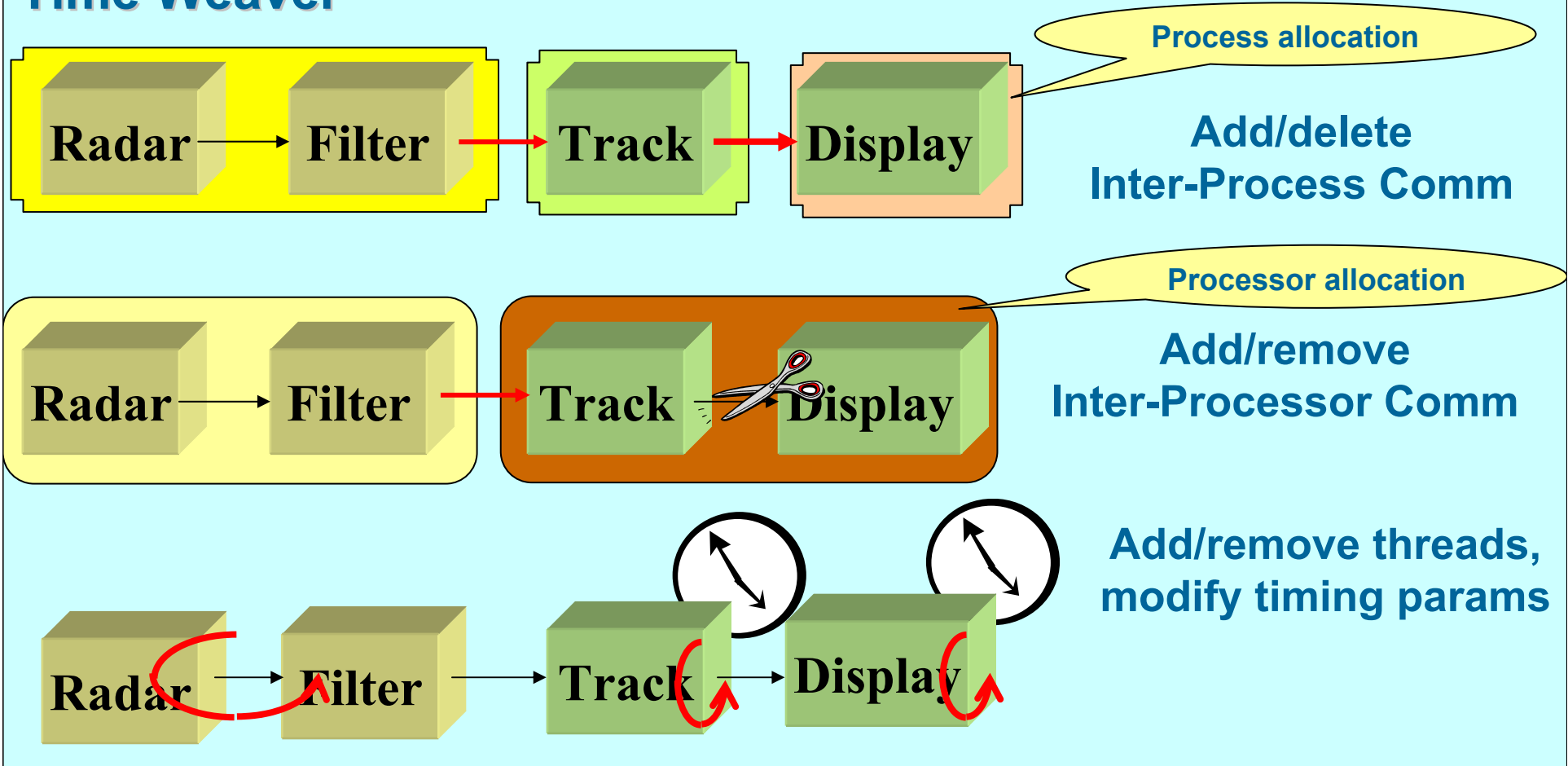
Multi-View Modeling + Analyses + Targeting Freedom + Reusable Embedded Software Components

Capability Summary



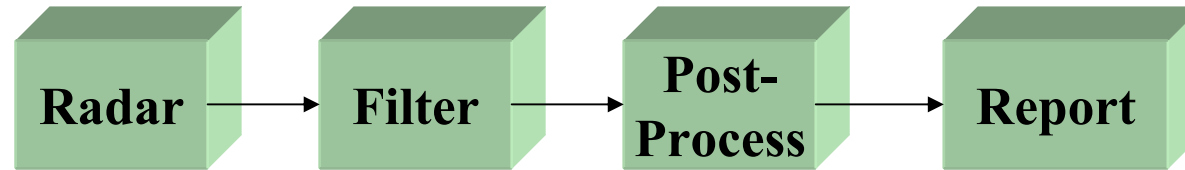
“Functional Coding Only”

Time Weaver

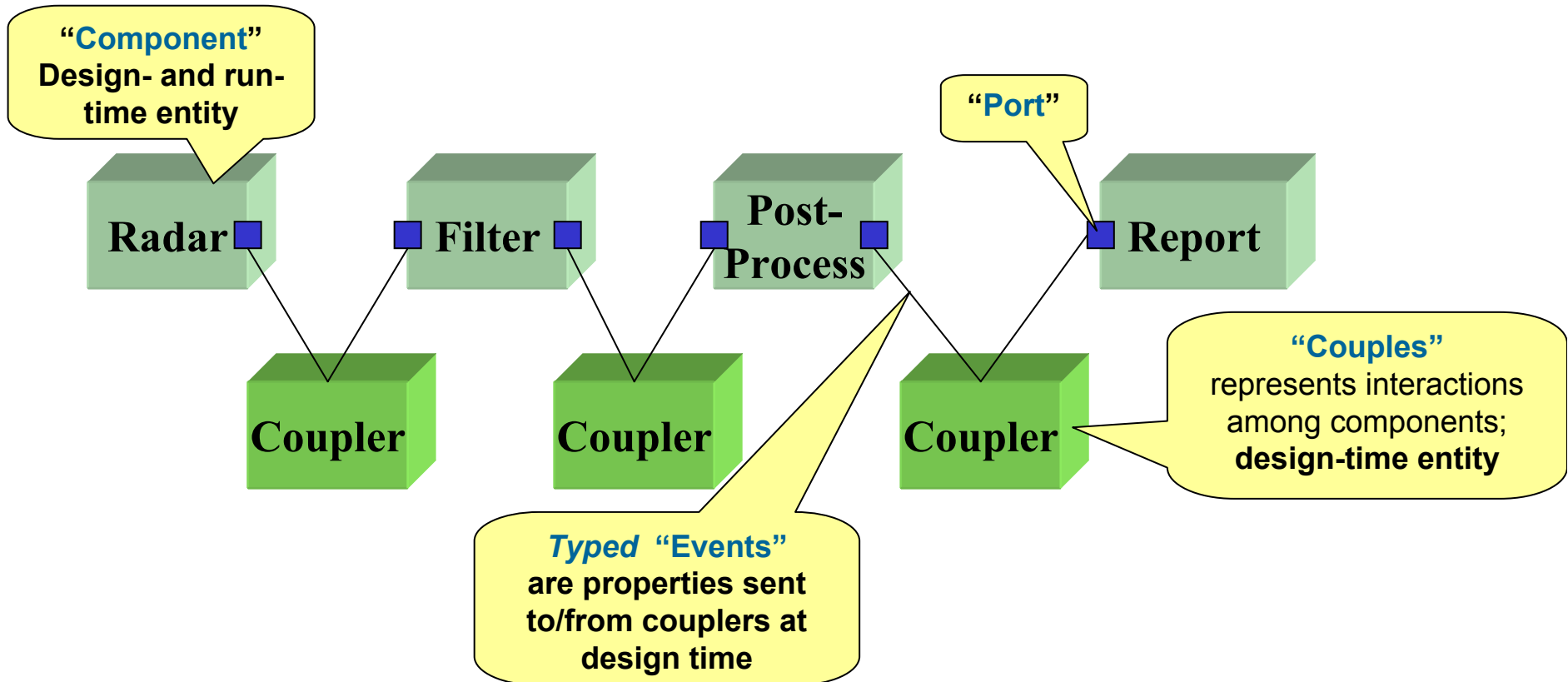


Time Weaver Abstractions

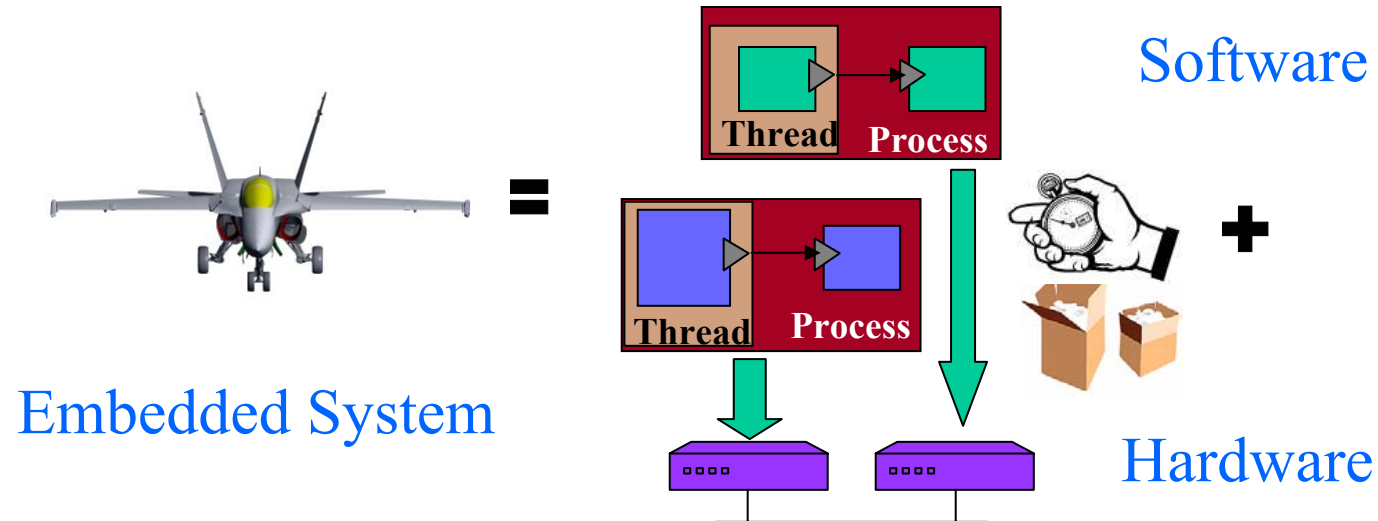
Logical View



First-Level Time Weaver Representation

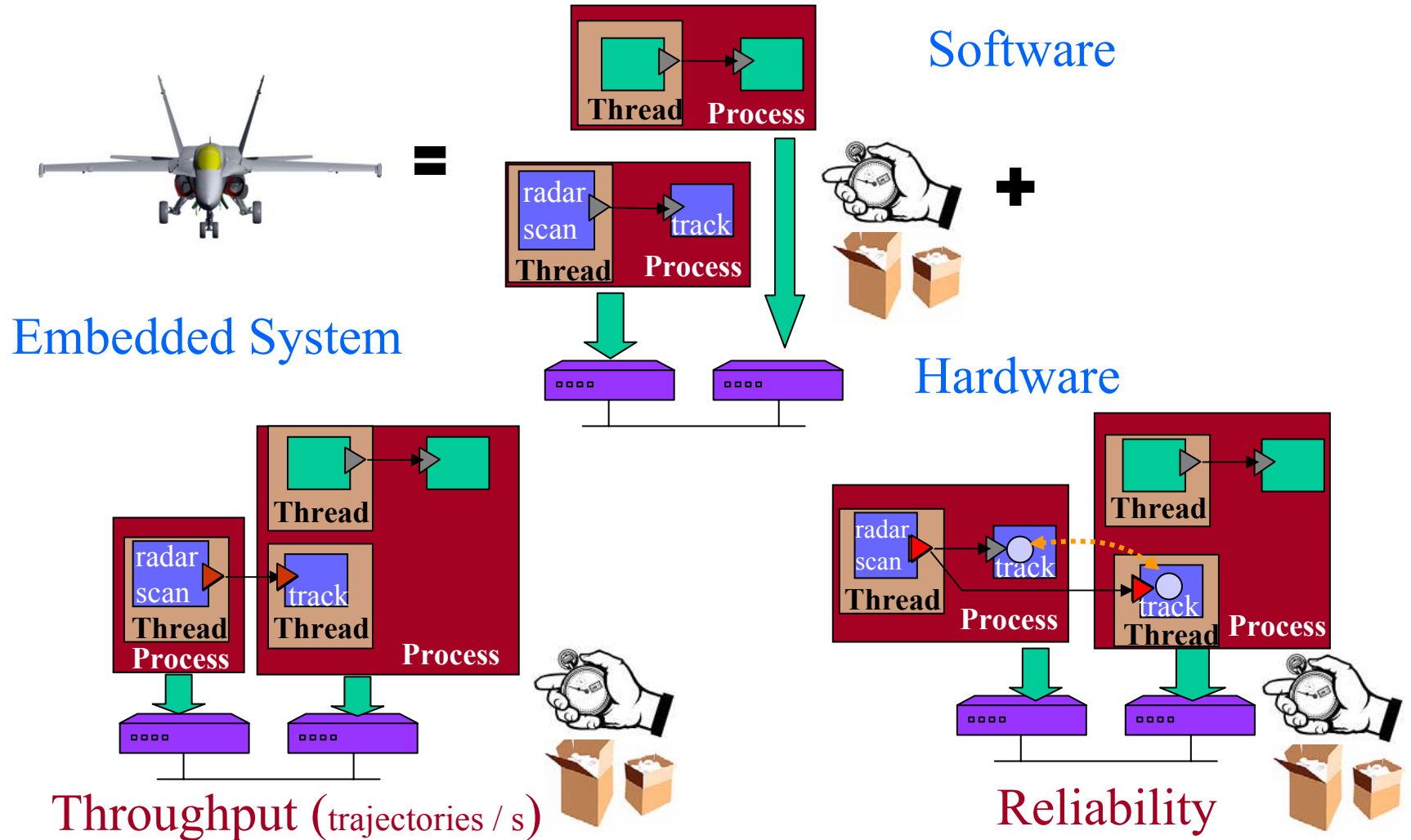


Embedded Systems Composition

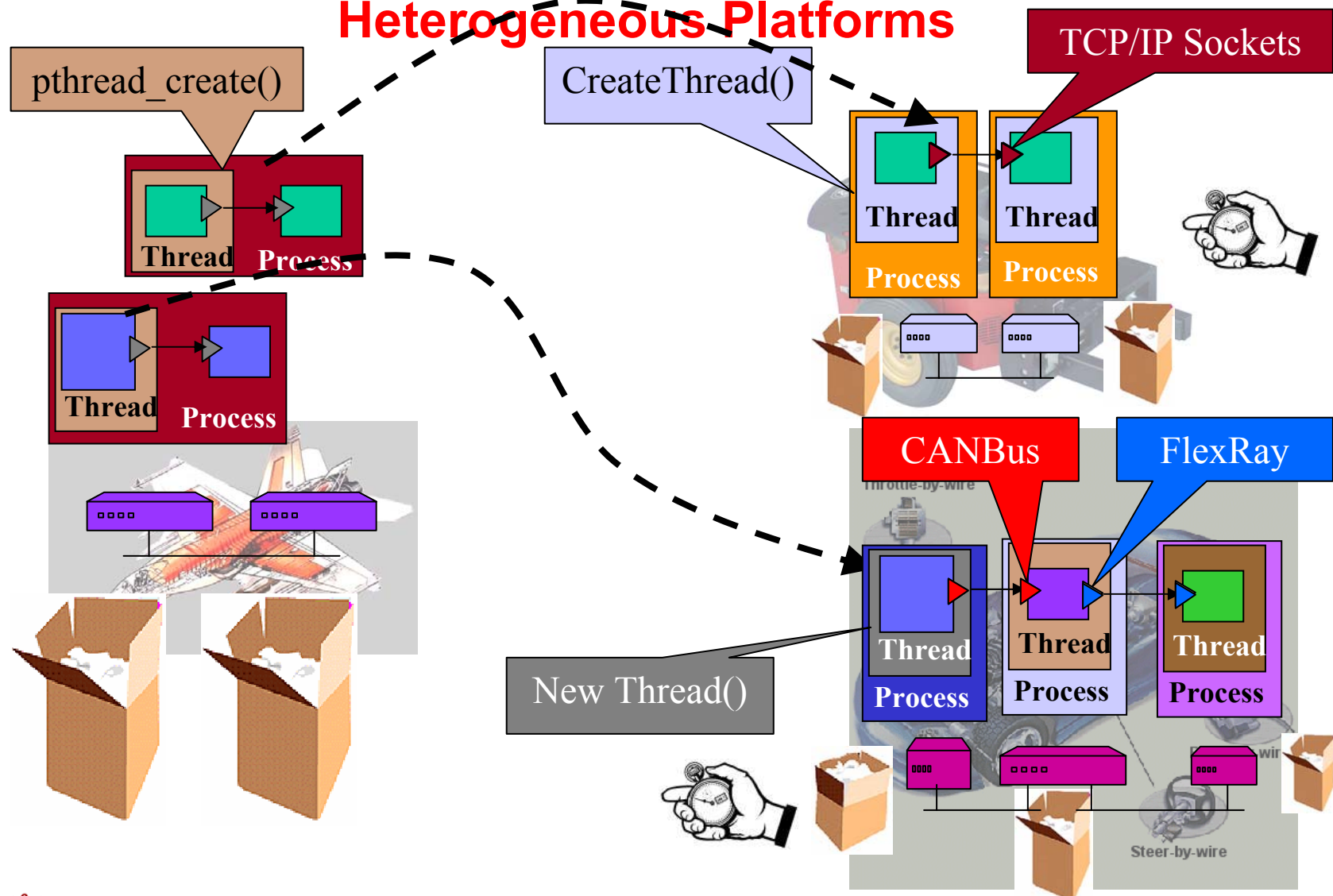


Embedded Software

Different Para-Functional Properties



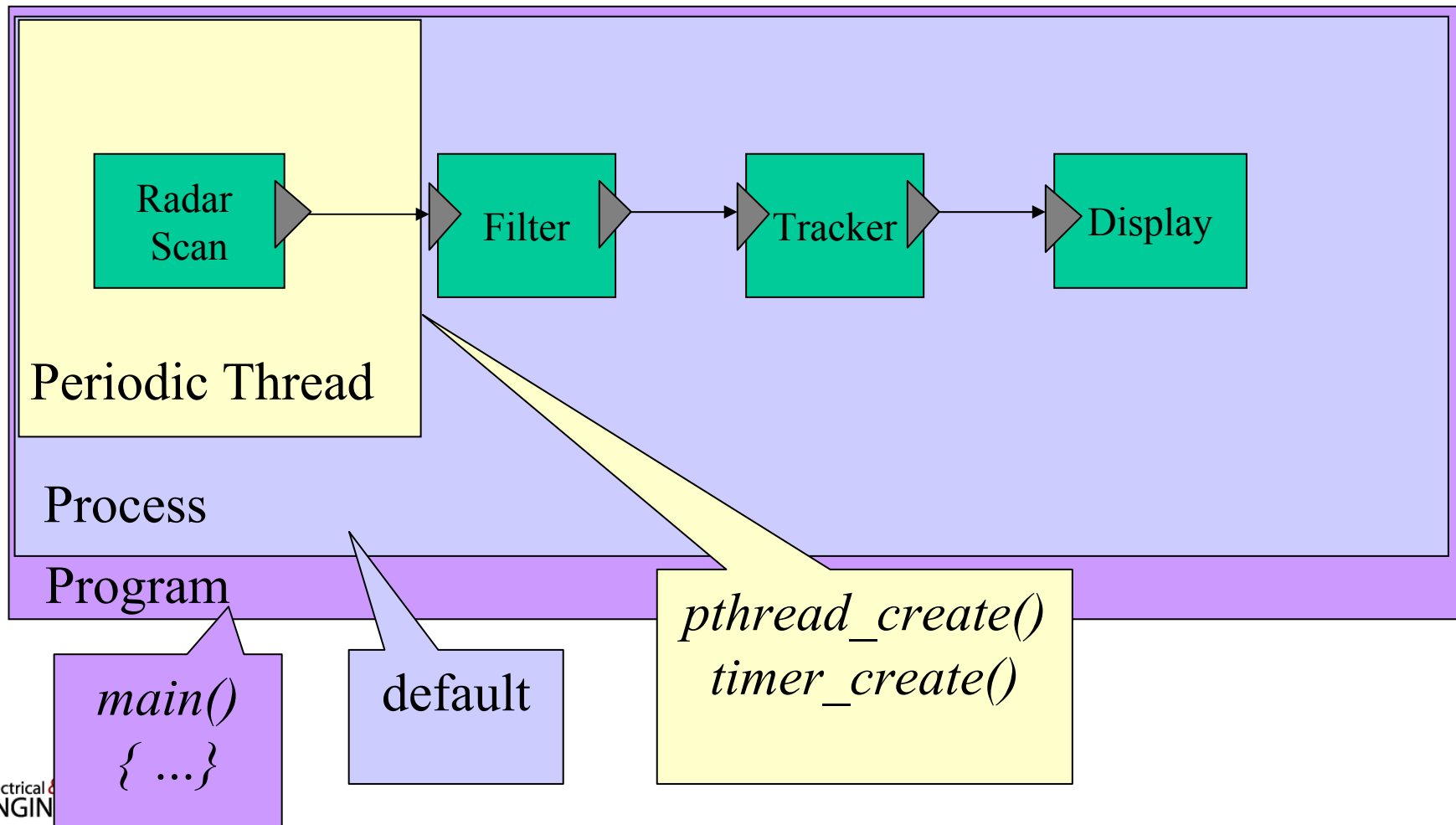
Embedded Software Heterogeneous Platforms



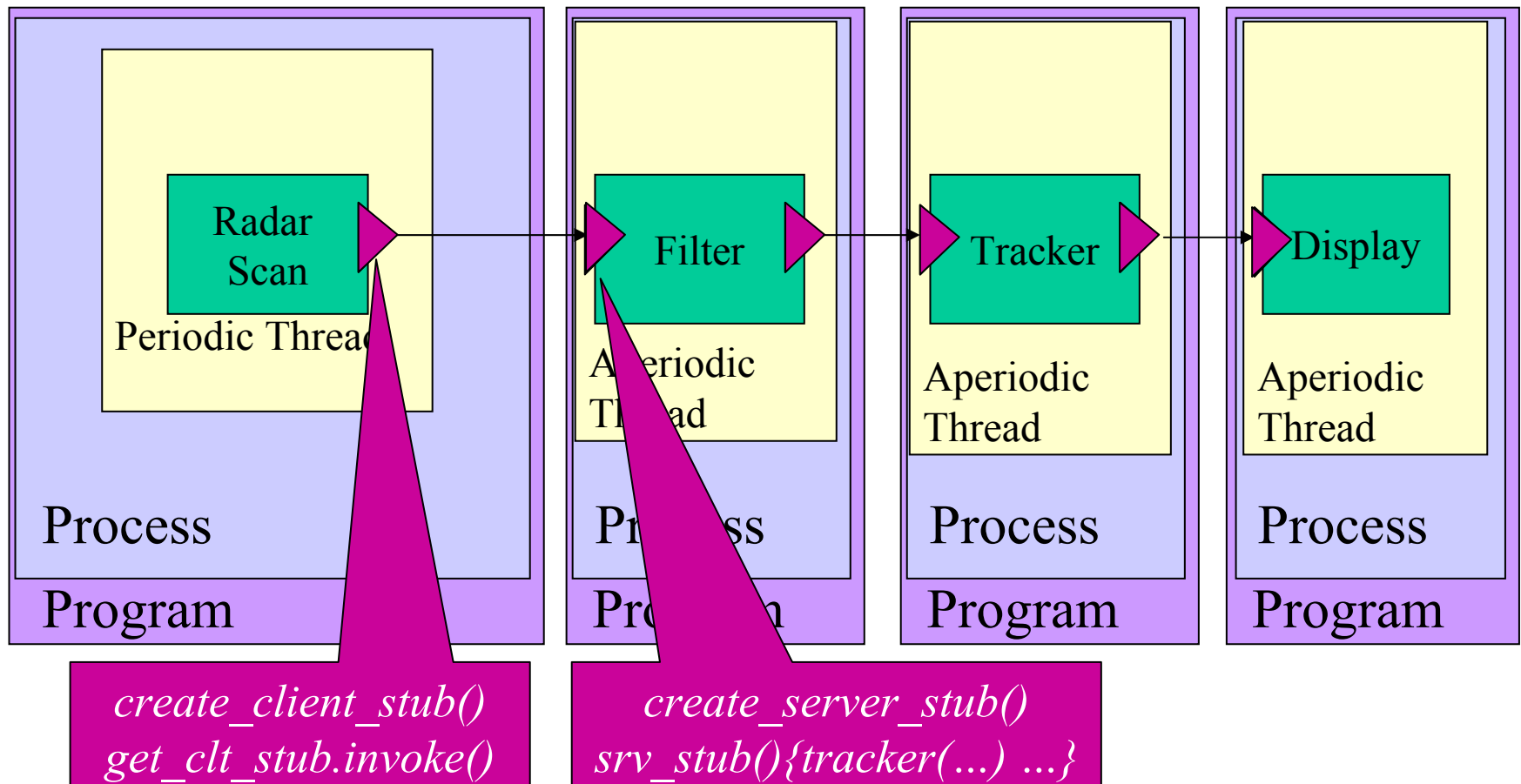
Recent Focus

- **Software Reuse** Through Software Components
- **Complexity Reduction**
- **Automatic Verification** of Para-Functional Properties
- **Synthesis**

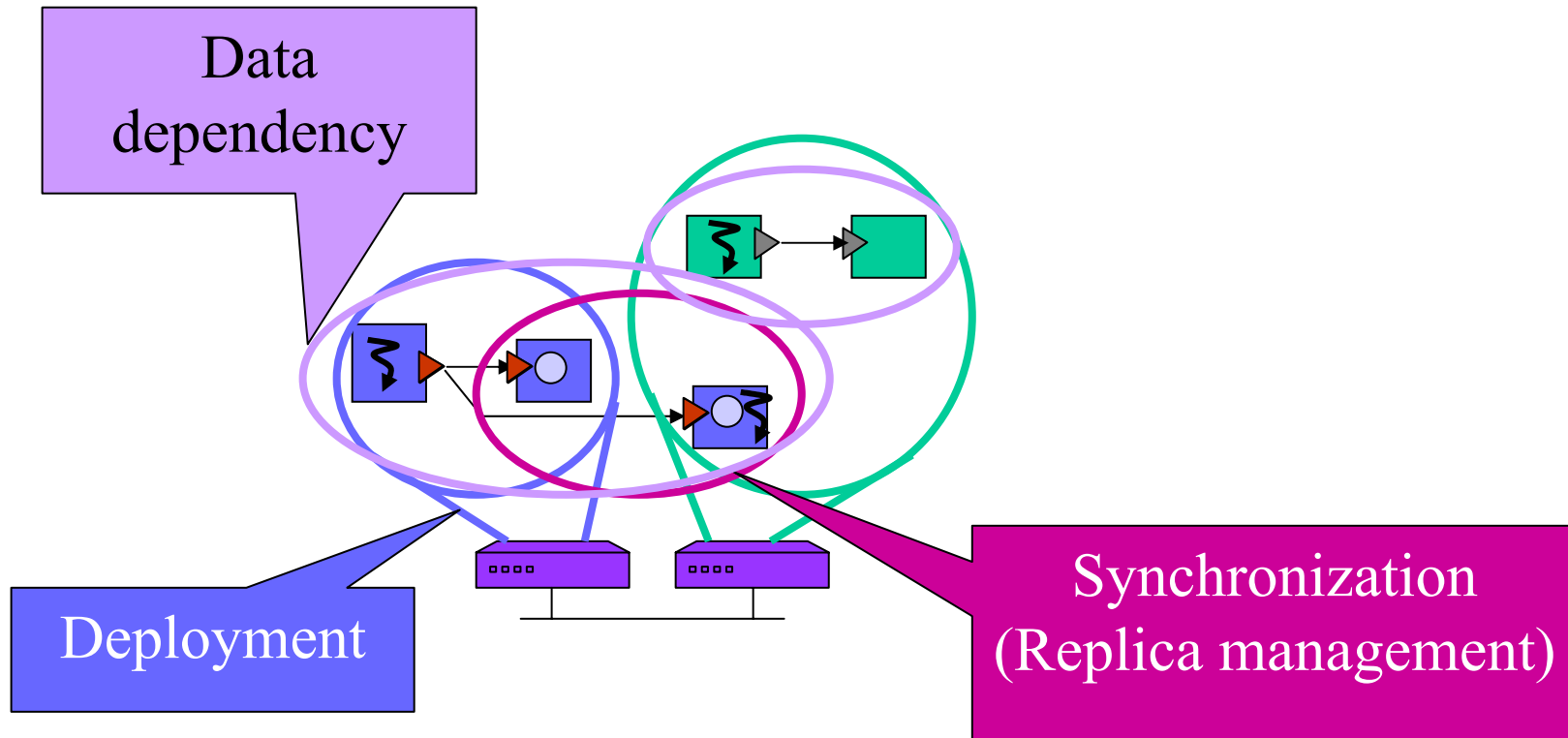
Traditional Process Radar



Traditional Process Pipeline Radar

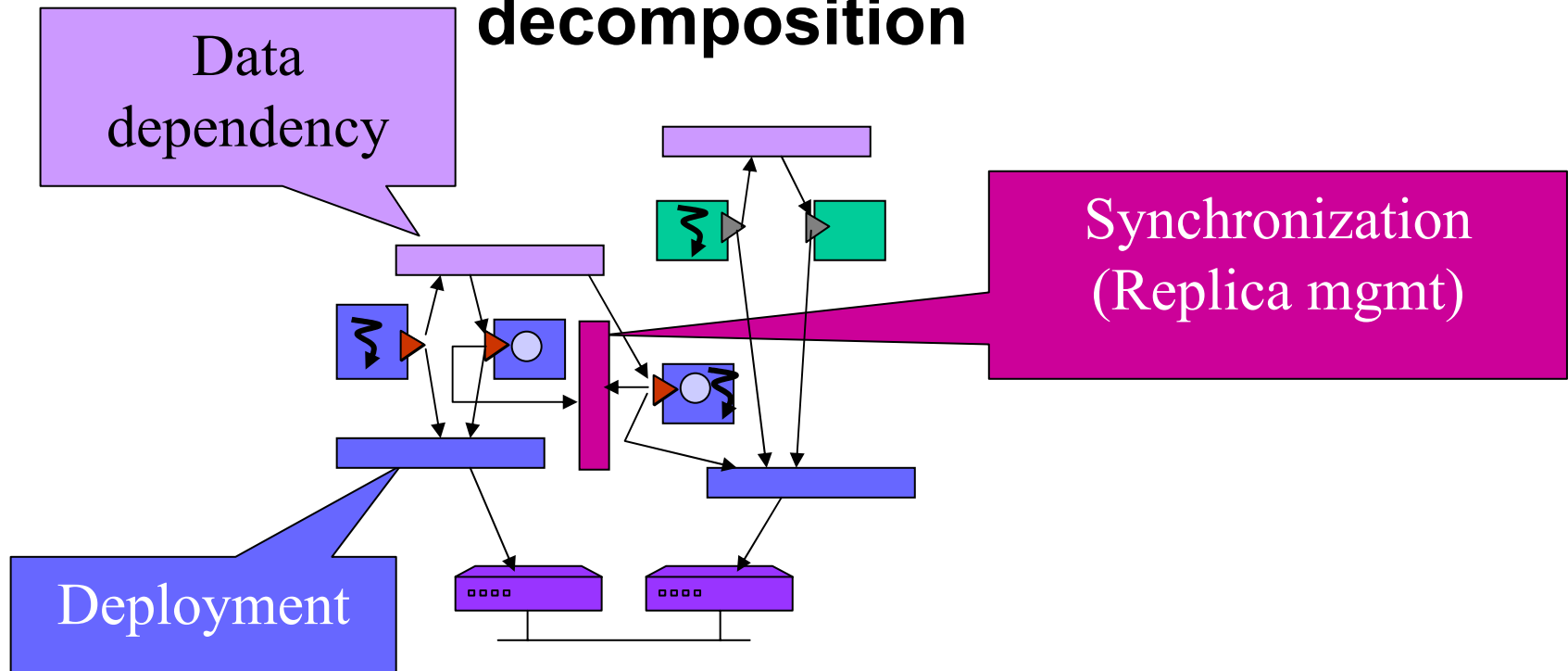


Inter-component relationships decomposition



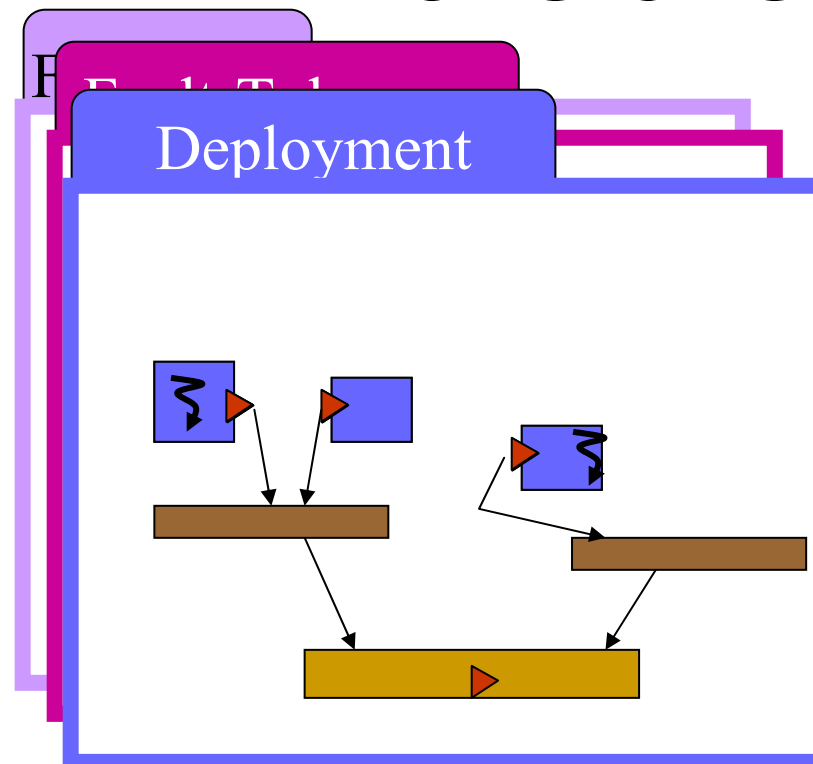
Coupler

Inter-component relationships decomposition



Coupler manipulate port elements to construct relationship

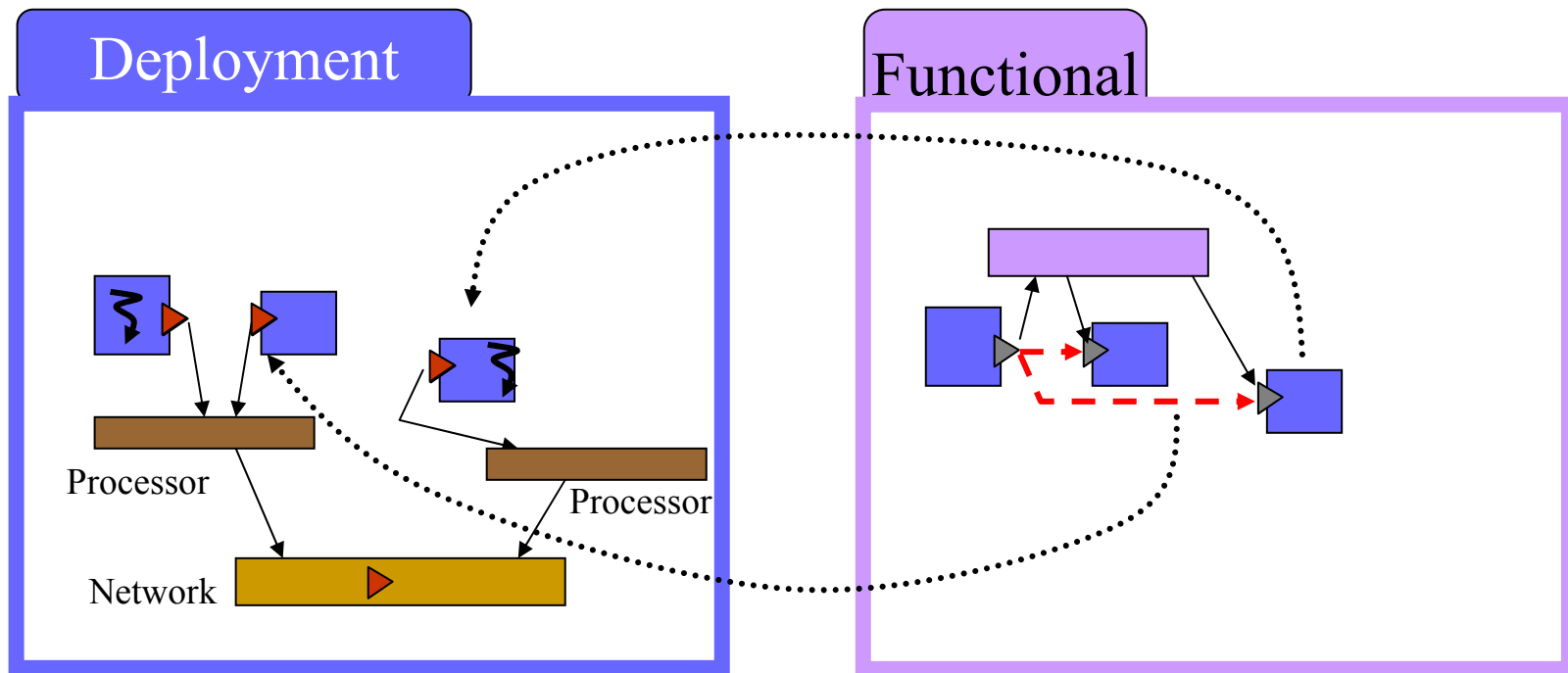
Independent Semantic Dimensions



Semantic separation

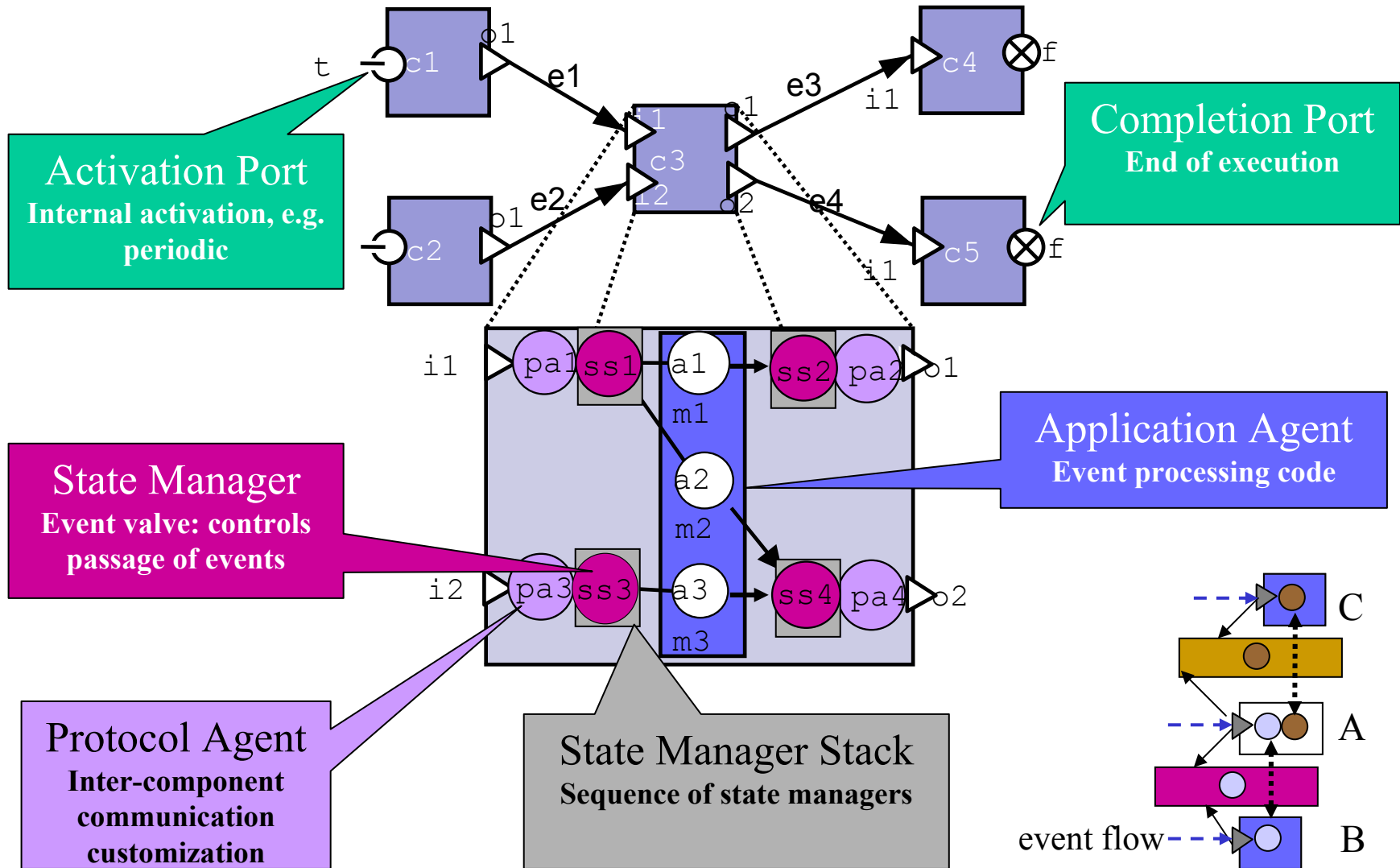
Projections to other dimensions

Inter-dimensional projections



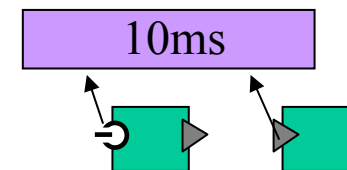
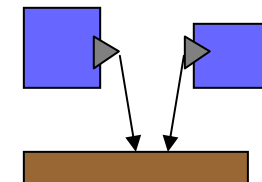
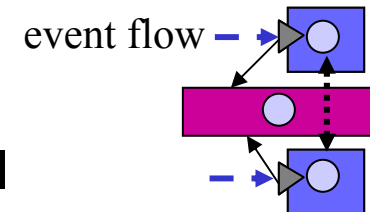
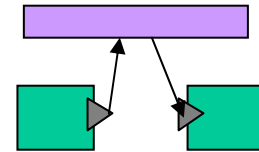
Software Model

Directed Graph

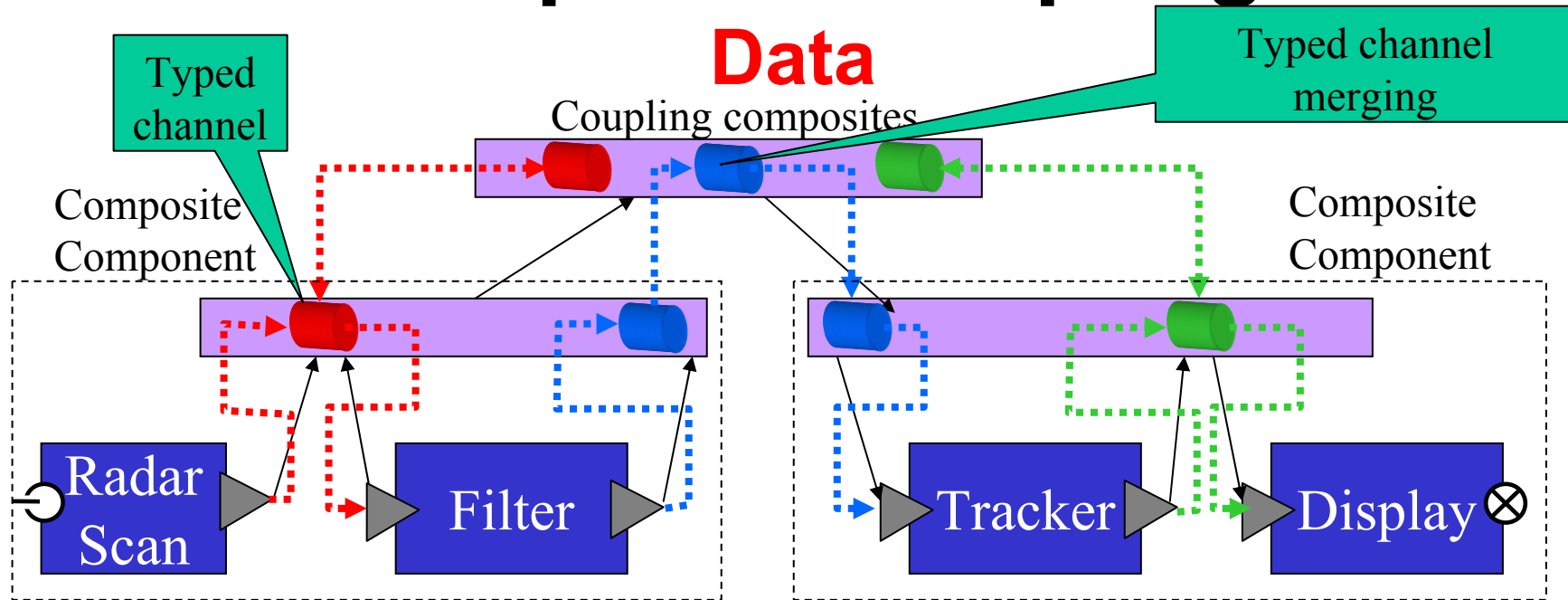


Basic Coupling

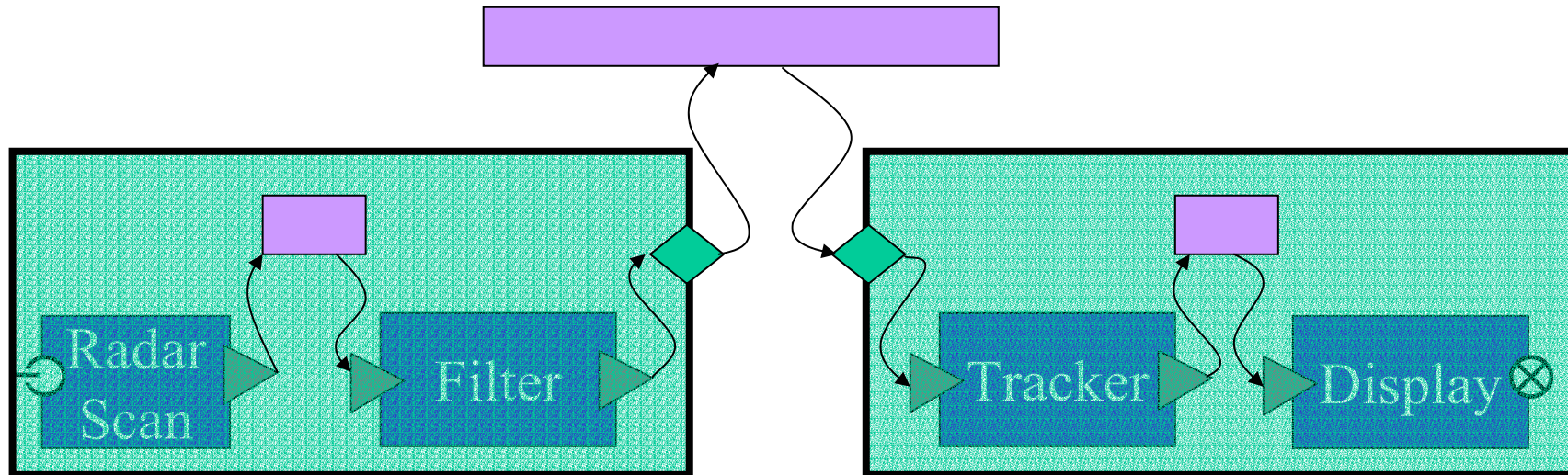
- Event Communication
 - Protocol agents interconnected
- Synchronization
 - State Managers = event valves
 - Open/close based on synch protocol
- Aggregation
 - Deploy together
- Related properties
 - Periodic execution



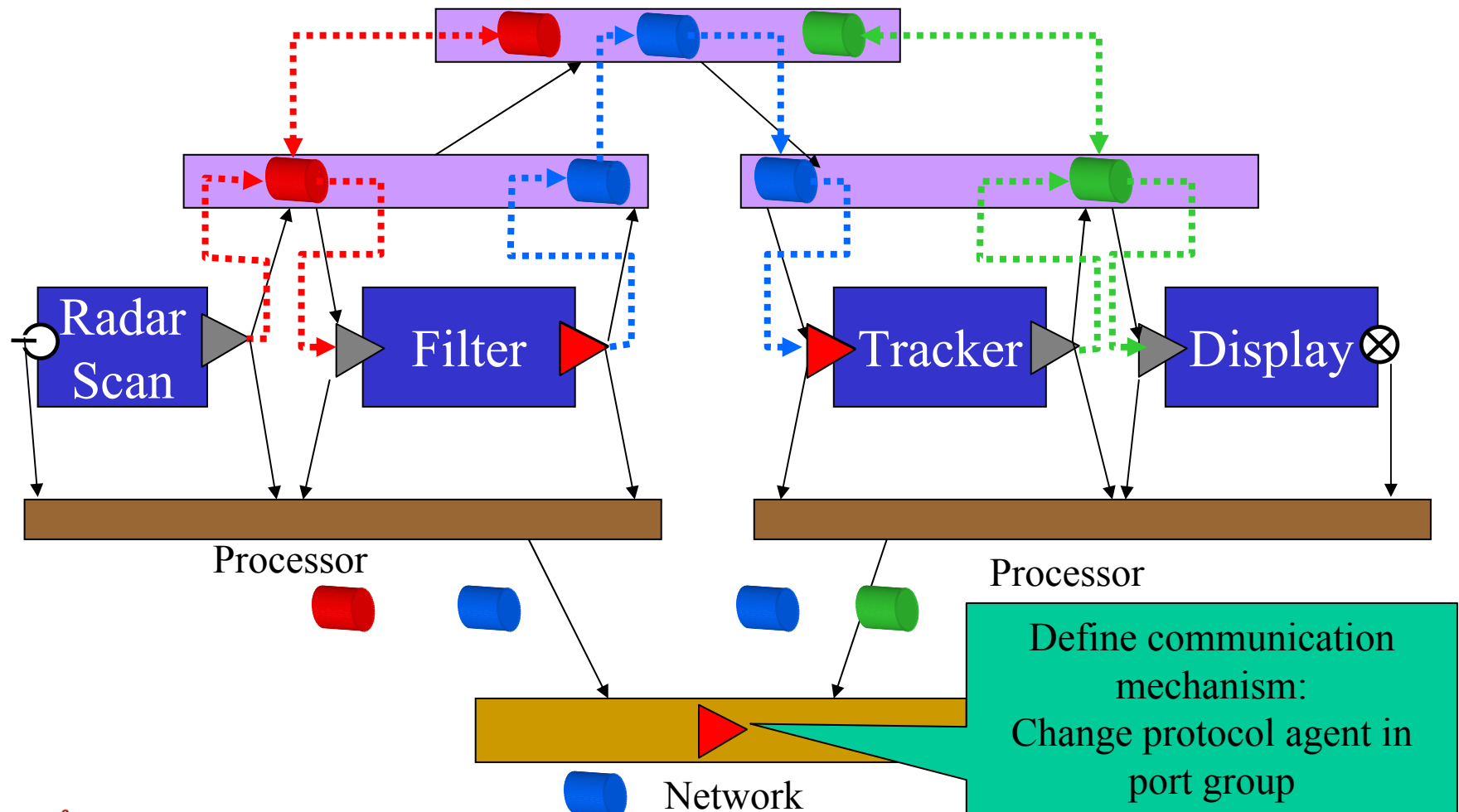
Composite Coupling



Composite Coupling Encapsulation

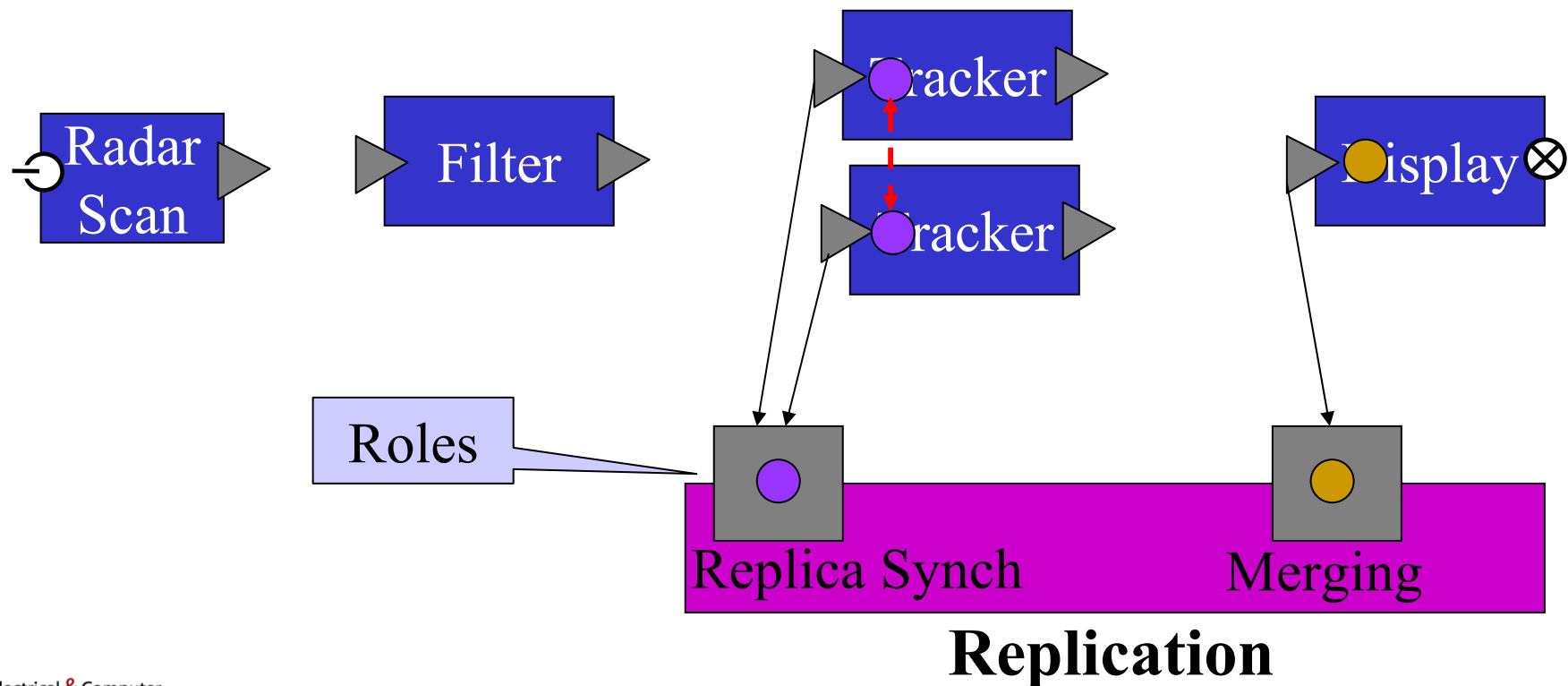


Composite Coupling Deployment



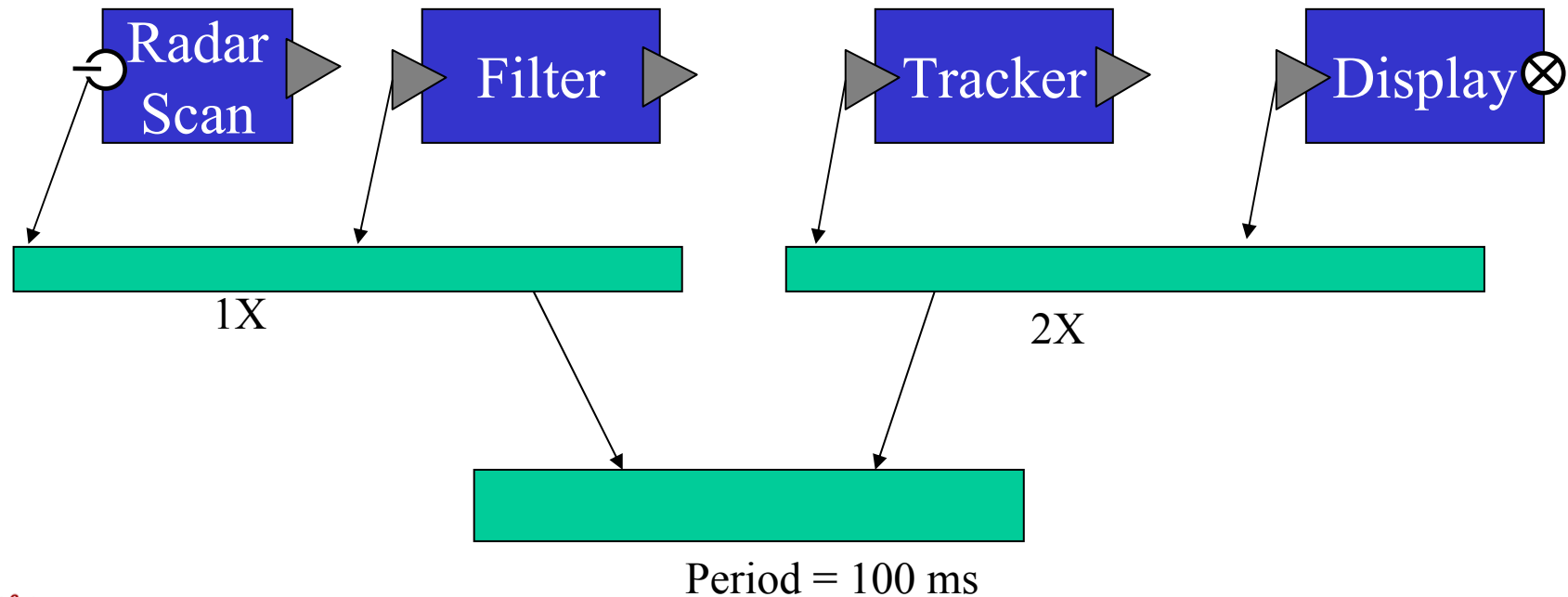
Composite Coupling

Synchronization



Composite Coupling

Timing Properties

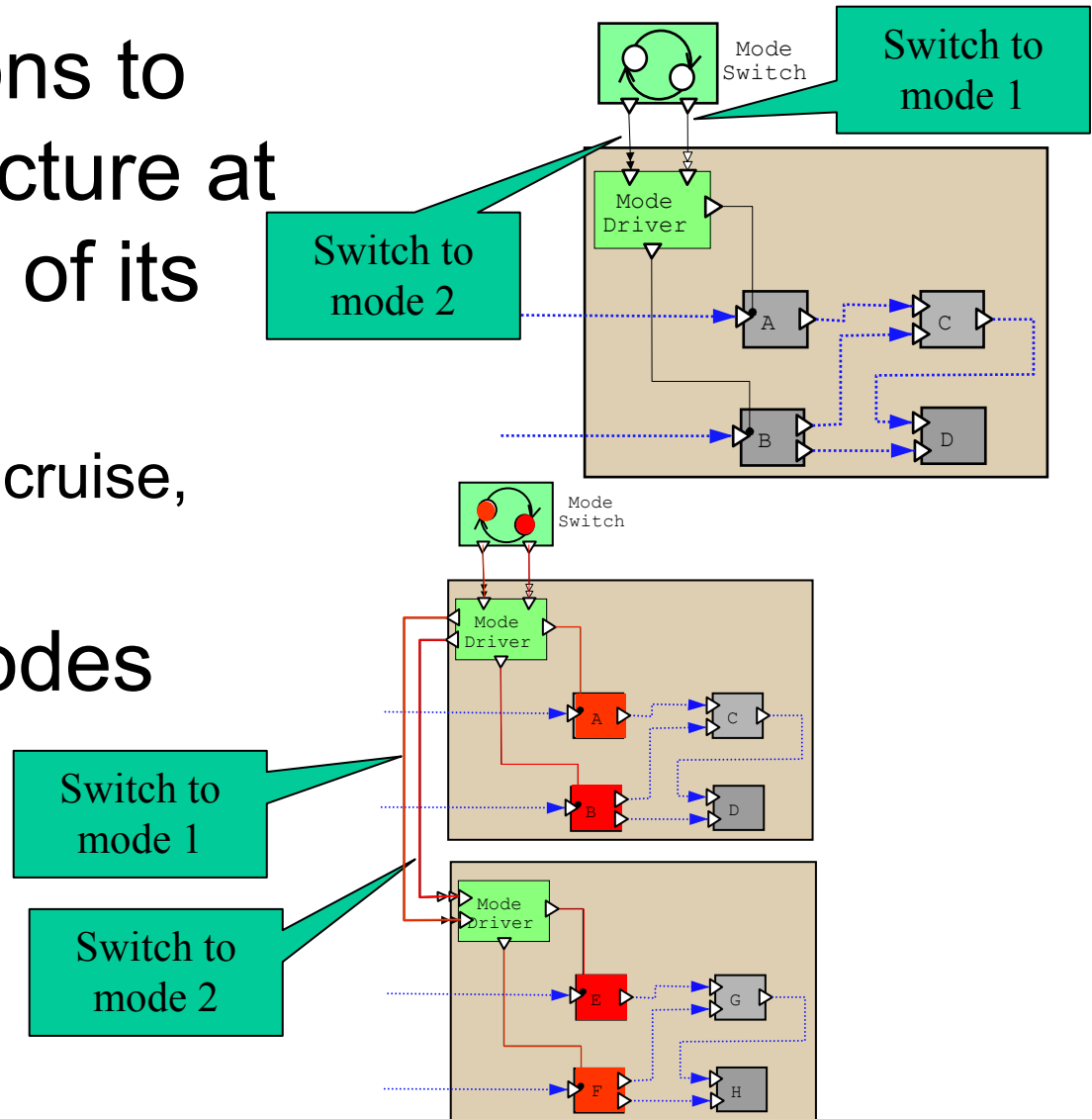


Embedded System Dimensions

- Functional
 - Event flow
- Timing
- Deployment
- Fault-Tolerance
- Modality
- Concurrency

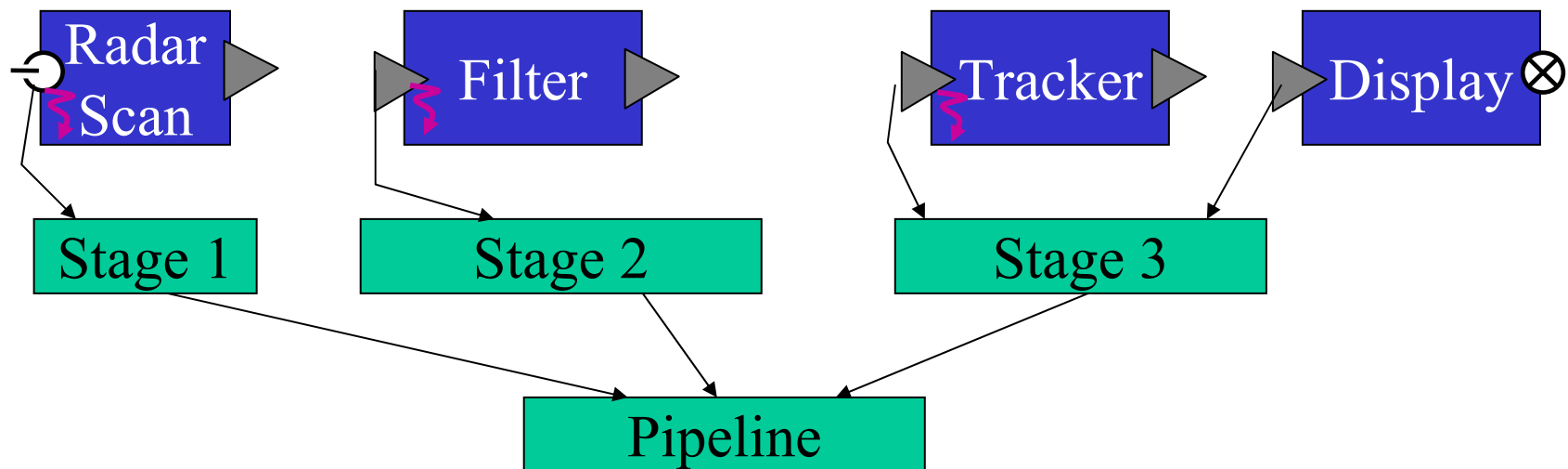
Modality

- Defines variations to the system structure at different stages of its lifetime
 - Avionics: takeoff, cruise, landing
- Hierarchy of modes



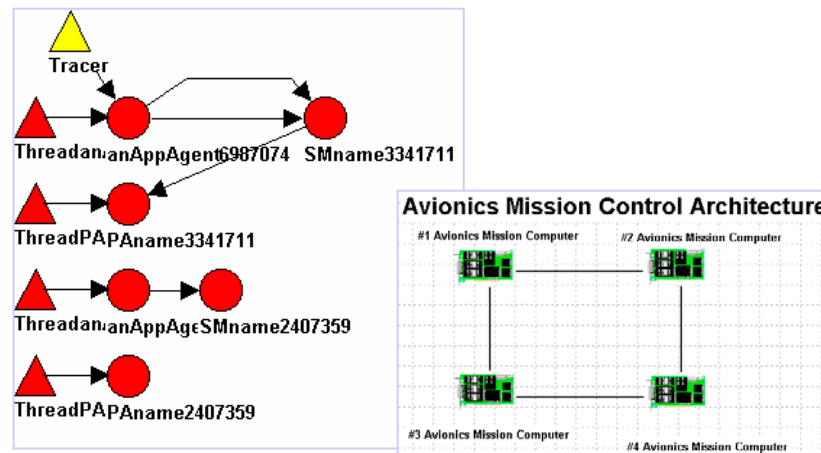
Concurrency

- Structures for concurrent execution
 - Pipeline
- Synchronization of concurrent activities



Automatic Software Model for Verification

- Generation of response chain and hardware model
- Integration with real-time analysis tools for automatic analysis (TimeWiz[®])



Code Generation

- Components can have multiple implementations
 - C, C++, Real-Time Java, Matlab, XML, ...
- Target Multiple Platforms
 - RT-CORBA, RMI, ...

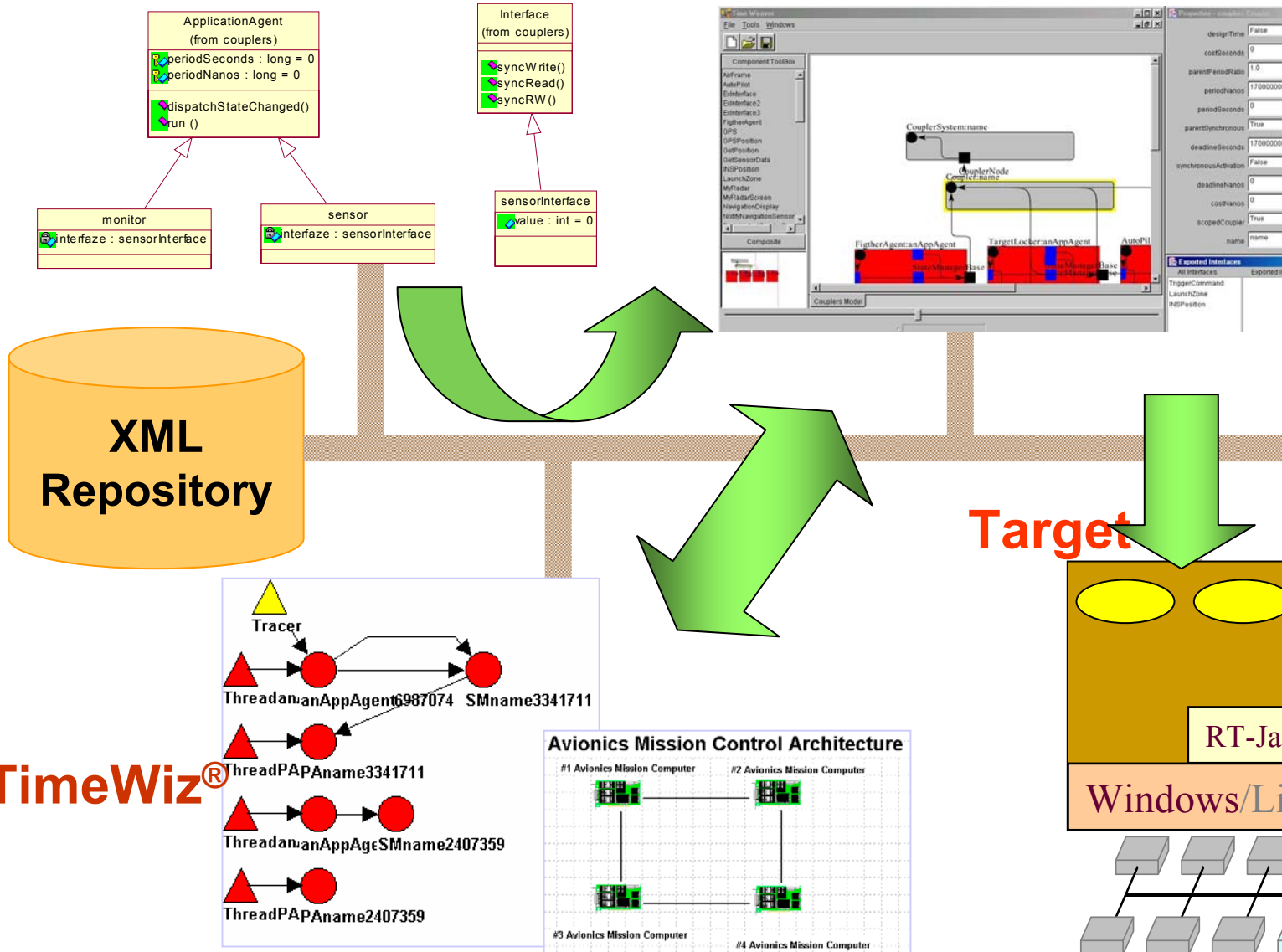
Optimization

- Automatic selection of optimal communication mechanism
- Synthesis
 - Deployment
 - Hardware Sizing

Tool Integration

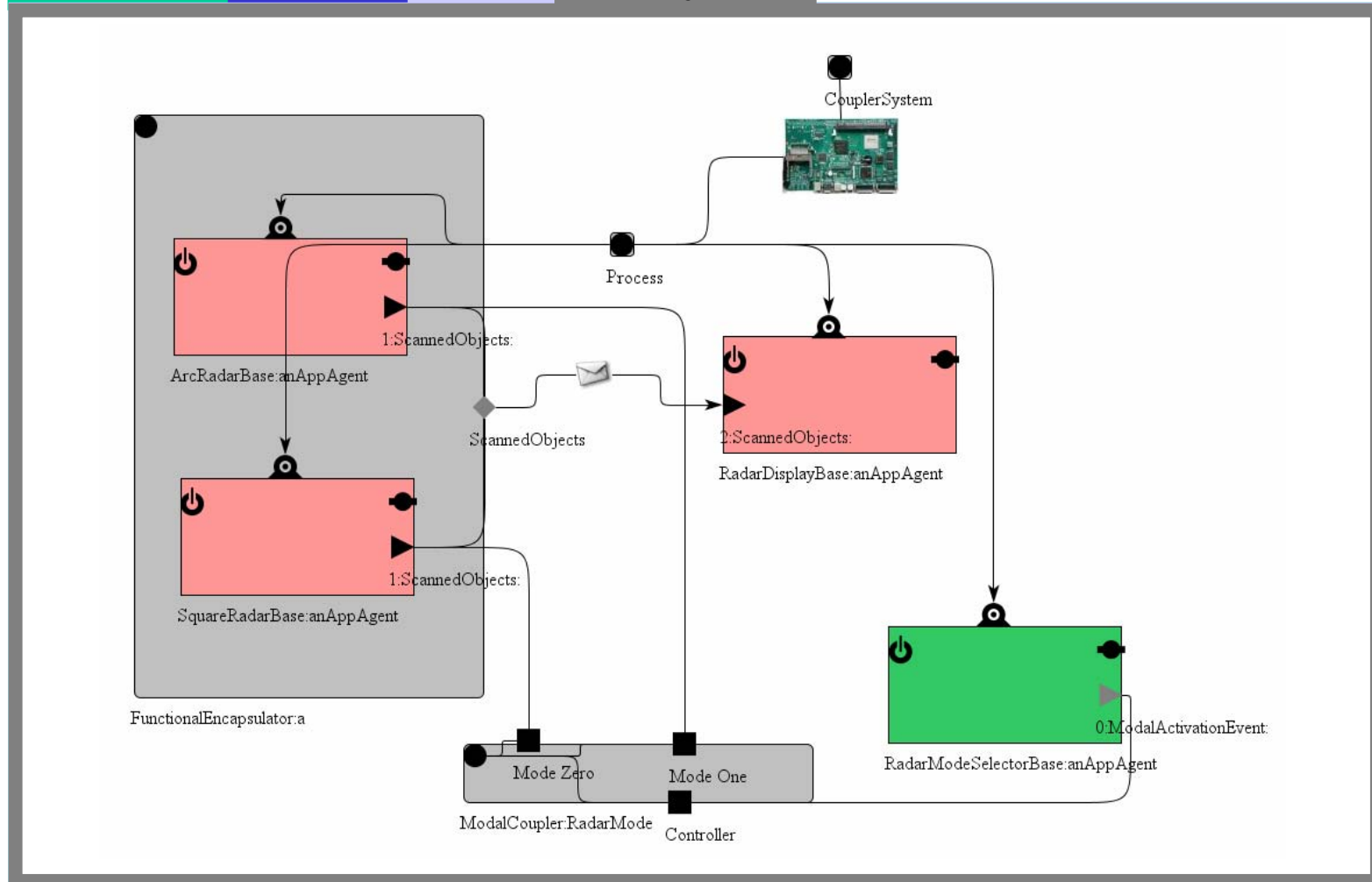
Rational® Rose UML

Time Weaver



Example

Event Flow Modality Timing Deployment



Case Studies

- **Avionics** Application Modeling
 - (~400 components)
- **Software Radio** Modeling
 - Data Flow
 - Throughput increase
- **Automotive** Testbed
 - Code generation for ARM 7 + μ COS-II
 - Working on: MPC555 + OSEKWorks

Related Work

- Software Architecture
- Meta-H
 - Component-based, Timing Analysis
 - No separate views
- AIRES
 - Hierarchical SM, control driver + functions
 - Timing Analysis
- Ptolemy II
 - Hierarchy of model of computation
 - Simulation
- AOP

Concluding Remarks

- Para-functional requirements – first-class entities
- Couplers – para-functional decomposition abstraction
- Multiple separate dimensions
- Automatic verification
- Code generation
- Tool integration